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# Blow-up of Solutions for a Reaction-diffusion Equation with Nonlinear Nonlocal Boundary Condition

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#### Authors' contributions

 $\label{eq:constraint} This work \ was \ carried \ out \ in \ collaboration \ between \ all \ authors. \ All \ authors \ read \ and \ approved \ the final \ manuscript.$ 

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# Abstract

This paper deals with a reaction-diffusion equation subject to nonlinear nonlocal boundary condition and with nonlocal reaction source. We investigate the global existence and blow up in finite time of a nonnegative solution by using a sub-super solution method.

Keywords: Reaction-diffusion equation; nonlocal source; nonlinear nonlocal boundary condition; blow-up; global solution.

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### **1** Introduction

In this paper we consider the following nonlocal initial boundary value problem

$$u_t = \Delta u + c(x,t)u^p \int_{\Omega} u^q(y,t)dy, \quad x \in \Omega, 0 < t < T,$$
(1.1)

$$\frac{\partial u}{\partial \nu} = \int_{\Omega} k(x, y, t) u^{l}(y, t) dy, \quad x \in \partial\Omega, 0 < t < T,$$
(1.2)

$$u(x,0) = u_0(x), \quad x \in \Omega, \tag{1.3}$$

where p, q, l > 0,  $\Omega$  is a bounded domain in  $\mathbb{R}^n (n \geq 1)$  with smooth boundary  $\partial\Omega$ ,  $\nu$  is unit outward normal on  $\partial\Omega$ . Here c(x,t) is a positive continuous bounded function defined for  $x \in \overline{\Omega}$ ,  $t \in [0,T]$  and k(x,y,t) is a positive continuous bounded function defined for  $x \in \partial\Omega$ ,  $y \in \Omega$ , t > 0. Furthermore, we assume that  $k(x, \cdot, t) \neq 0$  for any  $x \in \partial\Omega$  and t > 0. The initial datum  $u_0(x) \in C^{2+\alpha}(\Omega) \cap C(\overline{\Omega})$  with  $0 < \alpha < 1$ , and further, we assume that  $u_0(x) \geq 0, \neq 0$  and satisfies the compatibility conditions.

In the past several decades, many physical phenomena were formulated into nonlocal mathematical models(see[1]-[6] and the references therein). There has been a considerable amount of literature dealing with the properties of solutions to local semilinear parabolic equation or systems of heat equations with homogeneous Diriclet boundary conditions or with nonlinear boundary conditions (see [7]-[13] and references therein). However, there are some important phenomena formulated as parabolic equations which are coupled with nonlocal boundary conditions in mathematical modeling such as thermoelasticity theory (see [14]-[19]).

The problem of nonlocal boundary value for linear parabolic equations of the type

$$u_t - Au = c(x)u, \quad x \in \Omega, t > 0, \tag{1.4}$$

$$u(x,t) = \int_{\Omega} \varphi(x,y)u(y,t)dy, \quad x \in \partial\Omega, t > 0,$$
(1.5)

$$u(x,0) = u_0(x), \quad x \in \Omega \tag{1.6}$$

with uniformly elliptic operator  $A = \sum_{i,j=1}^{n} a_{ij}(x) \frac{\partial^2}{\partial x_i \partial x_j} - \sum_{i=1}^{n} b_i(x) \frac{\partial}{\partial x_i}$  and  $c(x) \leq 0$  was studied by Friedman[20]. The global existence and monotonic decay of the solution of problem (1.4)-(1.6) were obtained under the condition  $\int_{\Omega} |\varphi(x, y)| dy < 1$  for all  $x \in \partial \Omega$ . And later the problem (1.4)-(1.6) with Au replaced by  $\Delta u$  and the linear term c(x)u replaced by the nonlinear term g(x, u)was discussed by Deng [21]. The comparison principle and the local existence were established. On the basis of Deng's work, Seo in [22] investigated the above problem with g(x, u) = g(u), by using the upper and lower solution's technique, he gained the blow-up condition of positive solution, and in the special case  $g(u) = u^p$  or  $g(u) = e^u$  he also derived the blow-up rate estimates. In[23], Pao gave the numerical solutions for diffusion equations with nonlocal boundary conditions. Parabolic with both nonlocal sources and nonlocal boundary conditions have been studied as well. For example, the problem of the form

$$u_t - \Delta u = \int_{\Omega} g(u(y,t)) dy,$$
$$Bu = \int_{\Omega} K(x,y) u(y,t) dy, \quad x \in \partial\Omega, t > 0,$$
$$u(x,0) = u_0(x), \quad x \in \Omega$$

was studied by Lin and Liu [24]. They established local existence, global existence and nonexistence of solutions and discussed the blow-up properties of solutions.

In recent years, the mathematical investigation of blow-up phenomena of solutions to parabolic equation and system subject to nonlinear nonlocal boundary conditions has received a great deal of attention. The following heat equation with nonlinear nonlocal boundary condition

$$u_t = \Delta u + c(x, t)u^p, \quad x \in \Omega, t > 0,$$
$$u(x, t) = \int_{\Omega} k(x, y, t)u^l(y, t)dy, \quad x \in \partial\Omega, t > 0,$$
$$u(x, 0) = u_0(x), \quad x \in \Omega,$$

were studied by Gladkov and Kim in [25]. Comparison principle, the uniqueness of solution with any initial data for  $\min(p, l) \ge 1$  and with nontrivial initial data otherwise, nonuniqueness of solution with trivial initial data for p < 1 or l < 1, local existence theorem had been proved. In [26] they gave some criteria for the existence of global behavior of the coefficients c(x, t) and k(x, y, t) as t tends to infinity. Cui and Yang in [7] investigated

$$u_t = \Delta u + c(x,t)u^p \int_{\Omega} u^q(y,t)dy, \quad x \in \Omega, t > 0,$$
$$u(x,t) = \int_{\Omega} k(x,y,t)u^l(y,t)dy, \quad x \in \partial\Omega, t > 0,$$
$$u(x,0) = u_0(x), \quad x \in \Omega,$$

they obtained some criteria which determine whether the solutions blow up in finite time or exist globally, moreover, the blow up rate estimates were also obtained.

In [27] and [28], Gladkov A. and Kavitova T. investigated the following problem

$$u_t = \Delta u + c(x,t)u^p, \quad x \in \Omega, t > 0,$$
  
$$\frac{\partial u}{\partial \nu} = \int_{\Omega} k(x,y,t)u^l(y,t)dy, \quad x \in \partial\Omega, t > 0,$$
  
$$u(x,0) = u_0(x), \quad x \in \Omega.$$

In that two articles, they gave the existence theorem of a local solution and studied the problem of uniqueness and nonuniqueness. Criteria on this problem which determine whether the solutions blow up in finite time for large or for all nontrivial initial data were also given.

Motivated by the above cited works, we aim to establish the global existence and finite time blow up of the solution for problem(1.1)-(1.3).

The plan of this paper is as follows: in the next section, we deals with maximum principle and comparison principle, and give local existence in time for the solution. In Section 3 we establish conditions for global existence and blow-up in finite time.

### 2 The Comparison Principle and Local Existence

In this section we start with the definition of supersolution and subsolution of problem (1.1)-(1.3). Then we present some material needed in the proof of our main results. For convenience, We set  $Q_T = \Omega \times (0,T), S_T = \partial \Omega \times (0,T)$ , and  $\Gamma_T = S_T \cup \overline{\Omega} \times \{0\}, T > 0$ .

**Definition 2.1.** We say that a nonnegative function  $\tilde{u} \in C^{2,1}(Q_T) \cap C(Q_T \cup \Gamma_T)$  is a subsolution of (1.1)-(1.3) if

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$$\tilde{u}_t \le \Delta \tilde{u} + c(x,t)\tilde{u}^p \int_{\Omega} \tilde{u}^q dx, \quad (x,t) \in Q_T,$$
(2.1)

$$\frac{\partial \tilde{u}(x,t)}{\partial \nu} \le \int_{\Omega} k(x,y,t) \tilde{u}^{l}(y,t) dy, \quad (x,t) \in S_{T},$$
(2.2)

$$\tilde{u}(x,0) \le u_0(x), \quad x \in \Omega.$$
 (2.3)

A supersolution  $\hat{u} \in C^{2,1}(Q_T) \cap C(Q_T \cup \Gamma_T)$  of problem (1.1)-(1.3) is defined analogously by the above inequalities with each inequality reversed. We say that u(x,t) is a solution of the problem (1.1)-(1.3) in  $Q_T$  if it is both a subsolution and supersolution of (1.1)-(1.3) in  $Q_T$ .

To prove the main results, we use the positiveness of solution.

**Lemma 2.1.** Suppose that  $u_0 \not\equiv 0$  in  $\Omega$  and u(x,t) is a solution of (1.1)-(1.3) in  $Q_T$ . Then u(x,t) > 0 in  $Q_T \cup \Gamma_T$ .

Proof. Since  $u_0 \neq 0$  and  $u_t - \Delta u = c(x,t)u^p \int_{\Omega} u^q(y,t) dy \geq 0$  in  $Q_T$ , by the strong maximum principle u(x,t) > 0 in  $Q_T$ . If  $u(x_0,t_0) = 0$  in some point  $(x_0,t_0) \in S_T$ , then it yields  $\partial u(x_0,t_0)/\partial \nu < 0$ , which contradicts (1.2).

**Lemma 2.2.** Let  $\hat{u}(x,t)$  and  $\tilde{u}(x,t)$  be a supersolution and subsolution of problem (1.1)-(1.3) in  $Q_T$ , respectively, with  $\hat{u}(x,0) \ge \tilde{u}(x,0)$  and  $\hat{u}(x,0) > 0$  in  $\Omega$ . If  $\min(p,q,l) < 1$ , we further assume that  $\tilde{u}(x,0) > 0$ . Then  $\hat{u}(x,t) \ge \tilde{u}(x,t)$  in  $Q_T \cup \Gamma_T$ .

*Proof.* Let  $\varphi(x,t) \in C^{2,1}(\bar{Q}_t)$  (0 < t < T) be a nonnegative function which satisfies homogeneous Neumann boundary condition. Multiplying (2.1) by  $\varphi$  and then integrating over  $Q_t$ , we obtain

$$\int_{\Omega} \tilde{u}(x,t)\varphi(x,t)dx \leq \int_{\Omega} \tilde{u}(x,0)\varphi(x,0)dx \\
+ \int_{0}^{t} \int_{\Omega} (\tilde{u}(x,\tau)\varphi_{\tau}(x,\tau) + \tilde{u}(x,\tau)\Delta\varphi(x,\tau) + c(x,\tau)\varphi(x,\tau)\tilde{u}^{p}(x,\tau) \int_{\Omega} \tilde{u}^{q}(x,\tau))dxd\tau \\
+ \int_{0}^{t} \int_{\partial\Omega} \varphi(x,\tau) \int_{\Omega} k(x,y,\tau)\tilde{u}^{l}(y,\tau))dydS_{x}d\tau.$$
(2.4)

On the other hand, the supersolution  $\hat{u}(x,t)$  satisfies

$$\int_{\Omega} \hat{u}(x,t)\varphi(x,t)dx \ge \int_{\Omega} \hat{u}(x,0)\varphi(x,0)dx$$

$$+ \int_{0}^{t} \int_{\Omega} (\hat{u}(x,\tau)\varphi_{\tau}(x,\tau) + \hat{u}(x,\tau)\Delta\varphi(x,\tau) + c(x,\tau)\varphi(x,\tau)\hat{u}^{p}(x,\tau) \int_{\Omega} \hat{u}^{q}(y,\tau)dy)dxd\tau$$

$$+ \int_{0}^{t} \int_{\partial\Omega} \varphi(x,\tau) \int_{\Omega} k(x,y,\tau)\hat{u}^{l}(y,\tau))dydS_{x}d\tau.$$
(2.5)

Put  $w(x,t) = \tilde{u} - \hat{u}$ , subtracting (2.5) from (2.4) and using mean value theorem, we get

$$\int_{\Omega} w(x,t)\varphi(x,t)dx \leq \int_{\Omega} w(x,0)\varphi(x,0)dx \\
+ \int_{0}^{t} \int_{\Omega} w(x,\tau)(\varphi_{\tau}(x,\tau) + \Delta\varphi(x,\tau) + p\theta_{1}^{p-1}c(x,\tau)\varphi(x,\tau) \int_{\Omega} \hat{u}^{q}(y,\tau)dy)dxd\tau \\
+ \int_{0}^{t} \int_{\Omega} q\tilde{u}^{p}c(x,\tau)\varphi(x,\tau) \int_{\Omega} w(y,\tau)\theta_{2}^{q-1}(y,\tau)dydxd\tau \\
+ \int_{0}^{t} \int_{\partial\Omega} l\varphi(x,\tau) \int_{\Omega} k(x,y,\tau)\theta_{3}^{l-1}(y,\tau)w(y,\tau)dydS_{x}d\tau,$$
(2.6)

where  $\theta_i(x,t)$ , (i = 1, 2, 3) are some positive continuous functions in  $\overline{Q}_t$  if  $\min(p, q, l) < 1$  and some nonnegative continuous functions in  $\overline{Q}_t$  otherwise.

The function  $\varphi(x,t)$  is defined as a solution of the following problem

$$\varphi_{\tau}(x,\tau) + \Delta\varphi(x,\tau) + p\theta_{1}^{p-1}c(x,\tau) \int_{\Omega} \hat{u}^{q}(y,\tau) dy \varphi(x,\tau) = 0, \quad (x,\tau) \in Q_{t},$$
$$\frac{\partial\varphi}{\partial\nu} = 0, \quad (x,\tau) \in S_{t},$$
$$\varphi(x,t) = \psi(x), \quad x \in \Omega,$$

where  $\psi(x) \in C_0^{\infty}(\Omega)$ ,  $0 \leq \psi(x) \leq 1$ . By virtue of the comparison principle for linear parabolic equations the solution  $\varphi(x,t)$  is nonnegative and bounded. By (2.6) and  $w(x,0) \leq 0$  we have

$$\int_{\Omega} w(x,t)\varphi(x,t)dx \le M \int_{0}^{t} \int_{\Omega} w_{+}(x,\tau)dxd\tau,$$
(2.7)

here we denote  $w_{+} = \max(0, w)$  and choose

$$M = q \sup_{Q_t} \tilde{u}^p(x,\tau) c(x,\tau) \varphi(x,\tau) \theta_2^{q-1}(x,\tau) + l |\partial \Omega| \sup_{\partial \Omega \times Q_t} k(x,y,\tau) \sup_{Q_t} \theta_3^{l-1}(x,\tau) \sup_{S_t} \varphi(x,\tau).$$

Since the inequality (2.7) holds for every function  $\psi(x)$ , we can choose a sequence  $\psi_n(x) \in C_0^{\infty}(\Omega)$ converging in  $L^1(\Omega)$  to the function

$$\gamma(x) = \begin{cases} 1, & w(x,t) > 0, \\ 0, & w(x,t) \le 0. \end{cases}$$

Substituting  $\psi_n(x)$  instead of  $\psi(x)$  in (2.7) and letting  $n \to \infty$ , one have

$$\int_{\Omega} w_{+}(x,t)dx \le M \int_{0}^{t} \int_{\Omega} w_{+}(x,\tau)dxd\tau.$$
(2.8)

By using of Gronwall inequality we obtain  $w_+(x,t) \leq 0$  which implies  $\hat{u}(x,t) \geq \tilde{u}(x,t)$  in  $Q_T \cup \Gamma_T$ .

Local in time existence of positive classical solutions of problem (1.1)-(1.3) can be obtained by using fixed point theorem, the representation formula and the contraction mapping argument as done in [27], since the proof is more or less standard, we omit it here.

**Theorem 2.3.** For some values of T problem (1.1)-(1.3) has maximal solution in  $Q_T$ .

### **3** Global Existence and Blow-up in Finite Time

**Theorem 3.1.** Assume that  $p + q \le 1, l \le 1$ . Then the solutions of problem (1.1)-(1.3) exist globally for any nonnegative initial data.

*Proof.* In order to prove this results, we construct a suitable explicit supersolution of (1.1)-(1.3) in  $Q_T$ . Since c(x,t) and k(x,y,t) are continuous functions, there exists a constant M such that  $c(x,t) \leq M$  and  $k(x,y,t) \leq M$ . Let  $\lambda_1$  and  $\varphi$  be the first eigenvalue and the corresponding function of the following problem:

$$\Delta \phi + \lambda \phi = 0, \quad x \in \Omega, \tag{3.1}$$

$$\phi(x) = 0, \quad x \in \partial\Omega, \tag{3.2}$$

It is well known that  $\phi(x) > 0$  in  $\Omega$  and  $\max_{\partial \Omega} \partial \phi(x) / \partial \nu < 0$ . Furthermore, we choose  $0 < \varepsilon < 1$  such that

$$\int_{\Omega} \frac{1}{(\phi(x) + \varepsilon)^q} dx \le 1, \int_{\Omega} \frac{1}{(\phi(x) + \varepsilon)^l} dx \le 1.$$

Let  $\hat{u}(x,t)$  be defined as

$$\hat{u}(x,t) = \frac{d\exp(bt)}{\phi(x) + \varepsilon},$$

where constants d, b will be determined later to guarantee that  $\hat{u}$  is a supersolution of problem (1.1)-(1.3). After a direct computation, when  $(x,t) \in Q_T$ , we have

$$\hat{u}_{t} - \Delta \hat{u} - c(x,t) \hat{u}^{p} \int_{\Omega} \hat{u}^{q} dx$$

$$= b\hat{u} - \left(\frac{\lambda_{1}}{\phi(x) + \varepsilon} + \frac{2|\nabla \phi|^{2}}{(\phi(x) + \varepsilon)^{2}}\right) \hat{u} - c(x,t) \hat{u}^{p+q} (\phi(x) + \varepsilon)^{q} \int_{\Omega} \frac{1}{(\phi(x) + \varepsilon)^{q}} dx$$

$$\geq b\hat{u} - \left(\frac{\lambda_{1}}{\phi(x) + \varepsilon} + \frac{2|\nabla \phi|^{2}}{(\phi(x) + \varepsilon)^{2}}\right) \hat{u} - M[\sup_{\overline{\Omega}} (\phi(x) + \varepsilon)]^{q} \hat{u} \geq 0$$
(3.3)

if

$$d \ge \sup_{\bar{\Omega}} (\phi(x) + \varepsilon)$$

and

$$b \geq \frac{\lambda_1}{\varepsilon} + \sup_{\overline{\Omega}} \frac{2|\nabla \phi|^2}{(\phi(x) + \varepsilon)^2} + M[\sup_{\overline{\Omega}} (\phi(x) + \varepsilon)]^q.$$

When  $(x,t) \in S_T$ , we have

$$\frac{\partial \hat{u}}{\partial \nu} - \int_{\Omega} k(x, y, t) \hat{u}^{l}(y, t) dy$$

$$= \frac{-d \exp(bt)}{(\phi(x) + \varepsilon)^{2}} \frac{\partial \phi}{\partial \nu} - \int_{\Omega} k(x, y, t) \left(\frac{d \exp(bt)}{\phi(y) + \varepsilon}\right)^{l} dy$$

$$\geq d \exp(bt) \left(-\frac{\partial \phi}{\partial \nu} \frac{1}{\varepsilon^{2}} - M\right) \geq 0.$$
(3.4)

if we choose  $\varepsilon$  is small enough. It is clear from (3.1)-(3.2) that  $\hat{u}$  is a supersolution of problem (1.1)-(1.3) in  $Q_T$  if  $d > \sup_{\overline{\Omega}} u_0(x) + \sup_{\overline{\Omega}} (\phi(x) + \varepsilon)$ . Thus the solution of problem (1.1)-(1.3) exists globally.

**Theorem 3.2.** Assume that p + q < 1, l > 1. Then the solutions of problem (1.1)-(1.3) exist globally for small initial data.

*Proof.* Let  $\psi(x)$  be a positive solution of the following problem

$$-\Delta\psi(x) = 1, \quad x \in \Omega, \tag{3.5}$$

$$\frac{\partial \psi}{\partial \nu} = \delta, \quad x \in \partial \Omega. \tag{3.6}$$

We define the function  $\hat{u}(x,t) = a\psi(x)$ , after simple computation, we get

$$\hat{u}_t - \Delta \hat{u} - c(x,t) \hat{u}^p \int_{\Omega} \hat{u}^q dx$$
  
=  $-a\Delta \psi - c(x,t) a^{p+q} \psi^p \int_{\Omega} \psi^q(y) dy$   
 $\geq a \left( 1 - M a^{p+q-1} \max_{\Omega} \psi^{p+q} |\Omega| \right) \geq 0$  (3.7)

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for large values of a, since p + q < 1.

On the other hand, we have

$$\frac{\partial \hat{u}}{\partial \nu} = \delta \geq a M(\max_{\Omega} \psi)^l |\Omega| \geq \int_{\Omega} k(x,y,t) \hat{u}^l(y) dy$$

for small values of  $\max_{\Omega} \psi$  since l > 1. Hence  $\hat{u}(x,t)$  is a supersolution of (1.1)-(1.3) provided that  $u_0(x) \leq M\psi(x)$ . By the comparison principle, the problem of (1.1)-(1.3) has global solutions.  $\Box$ 

**Theorem 3.3.** Assume that p + q > 1, l > 0. Then the solutions of problem (1.1)-(1.3) blow up in finite time for any positive initial data.

Proof. Consider the ODE problem

$$\tilde{u}'(t) = m |\Omega| \tilde{u}^{p+q}, \quad \tilde{u}(0) = \tilde{u}_0,$$
(3.8)

where *m* is the lower bound of the functions c(x,t), k(x, y, t). As we all know, the solution to (3.8) blows up in finite time under the assumption p + q > 1. It is easy to see the solution of (3.8) is a subsolution of problem (1.1)-(1.3) if we choose  $\tilde{u}_0 = \min_{\overline{\Omega}} u_0(x)$ . By the comparison theorem, the solutions of problem (1.1)-(1.3) blow up in finite time.

**Theorem 3.4.** Assume that  $\min(p,q) > 1$ , l > 0. Then the solutions of problem (1.1)-(1.3) blow up in finite time for large initial data.

*Proof.* Let  $\phi$  be the eigenfunction of problem (3.1)-(3.2) corresponding to the first eigenvalue  $\lambda_1$ , which is chosen to satisfy that  $\int_{\Omega} \phi(x) dx = 1$ . Now we denote  $\phi_s = \sup_{\bar{\Omega}} \phi(x)$ , and introduce the following auxiliary function

$$w(t) = \int_{\Omega} u(x,t)\phi(x)dx.$$

Multiplying both sides of the equation of (1.1) by  $\phi(x)$  and integrating over  $\Omega$ , we have

$$w'(t) = \int_{\Omega} \left( \Delta u + c(x,t)u^p \int_{\Omega} u^q dx \right) \phi dx.$$

Then using (3.1),(3.2), Green's identity and the equality  $\int_{\partial\Omega} \frac{\partial\phi}{\partial\nu} = -\lambda_1$ , we obtain

Further, since p, q > 1, Jensen's inequality can be applied to (3.9) to get

$$w'(t) \ge -\lambda_1 w(t) + \frac{m}{\phi_s} w^{p+q}(t)$$

with the initial data  $w(0) = \int_{\Omega} u_0(x)\varphi(x)dx$ . Then if  $w(0) > (\frac{\lambda_1\phi_s}{m})^{\frac{1}{p+q-1}}$ , by the comparison principle for ordinary equations, we draw the conclusion.

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### **Competing Interests**

The authors declare that no competing interests exist.

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